

# Cs502 Solved MCQS for Final Term Without Repetitions

22/02/2013

## Question # 1

Word Algorithm comes from the name of the Muslim author:

**Abu Ja'far Mohammad ibn Musa al-Khwarizmi. (p7)**

## Question # 2

Al-Khwarizmi's work was written in a book titled

**al Kitab al-mukhtasar fi hisab al-jabr wa'l-muqabalah (p7)**

## Question # 3

The running time of quick sort depends heavily on the selection of:

No of inputs

Arrangement of elements in array

Size of elements

**Pivot element (p49)**

## Question # 4

Which sorting algorithm is faster?

$O(n^2)$

$O(n \log n)$

**$O(n+k)$  (p58)**

$O(n^3)$

## Question # 5

There is relationship between number of **back edges** and **number of cycles** in DFS

Select correct option:

Both are equal.

Cycles are half of back edges.

Cycles are one fourth of back edges.

**There is no relationship between back edges and number of cycle (p131)**

## Question # 6

You have an adjacency list for G, what is the time complexity to compute Graph transpose  $G^T$ ?

Select correct option:

**$(V+E)$  (Reference)**

V.E

V

E

## Question # 7

**Dijkstra's algorithm:**

Has greedy approach to find all shortest paths

Has both greedy and dynamic approach to find all shortest paths

**Has greedy approach to compute single source shortest paths to all other vertices (p154)**

Has both greedy and dynamic approach to compute single source shortest paths to all other vertices.

## Question # 8

What is the time complexity to **extract a vertex** from the **priority queue** in **Prim's algorithm**?

Select correct option:

$O(\log E)$

$(V)$

$(V+E)$

**$O(\log V)$  (p152)**

#### Question # 9

Which is true statement in the following?

Kruskal algorithm is multiple source technique for finding MST.

Kruskal's algorithm is used to find minimum spanning tree of a graph, time complexity of this algorithm is  $O(EV)$

Both of above

**Kruskal's algorithm (choose best non-cycle edge) is better than Prim's (choose best tree edge) when the graph has relatively few edges.**

#### Question # 11

Kruskal's algorithm (choose best non-cycle edge) is better than Prim's (choose best tree edge) when the graph has relatively few edges.

**True**

False

#### Question # 12

0-1 knapsack problem is called a "0-1" problem, because

**Each item must be entirely accepted or rejected (p92)**

#### Question # 13

Which statement is true?

Select correct option:

If a **dynamic-programming problem** satisfies the optimal-substructure property, then a locally optimal solution is globally optimal.

If a **greedy choice property** satisfies the optimal-substructure property, then a locally optimal solution is globally optimal.

**Both of above (p77, p98)**

None of above

#### Question # 14

A **dense undirected** graph is:

Select correct option:

**A graph in which  $E = O(V^2)$  (Reference)**

A graph in which  $E = O(V)$

A graph in which  $E = O(\log V)$

All items above may be used to characterize a dense undirected graph

#### Question # 15

What algorithm technique is used in the implementation of **Kruskal solution** for the MST?

**Greedy Technique (p142)**

Divide-and-Conquer Technique

Dynamic Programming Technique

The algorithm combines more than one of the above techniques

### Question # 16

A digraph is strongly connected under what condition?

A digraph is strongly connected if for every pair of vertices  $u, v \in V$ ,  $u$  can reach  $v$ .

**A digraph is strongly connected if for every pair of vertices  $u, v \in V$ ,  $u$  can reach  $v$  and vice versa. (p135)**

A digraph is strongly connected if for at least one pair of vertex  $u, v \in V$ ,  $u$  can reach  $v$  and vice versa.

A digraph is strongly connected if at least one third pair of vertices  $u, v \in V$ ,  $u$  can reach  $v$  and vice versa.

### Question # 17

The relationship between number of back edges and number of cycles in DFS is,

Both are equal

Back edges are half of cycles

Back edges are one quarter of cycles

**There is no relationship between no. of edges and cycles (p131)**

### Question # 18

Suppose that a graph  $G = (V, E)$  is implemented using adjacency lists. What is the complexity of a breadth-first traversal of  $G$ ? Select correct option:

$O(|V|^2)$

$O(|V| + |E|)$

$O(|V|^2|E|)$

**$O(|V| + |E|)$  (p116)**

### Question # 19

**Forward edge is?**

Select correct option:

$(u, v)$  where  $u$  is a proper descendent of  $v$  in the tree.

**$(u, v)$  where  $v$  is a proper descendent of  $u$  in the tree. (p129)**

$(u, v)$  where  $v$  is a proper ancestor of  $u$  in the tree.

$(u, v)$  where  $u$  is a proper ancestor of  $v$  in the tree.

### Question # 20

**Back edge is?**

Select correct option:

**$(u, v)$  where  $v$  is an ancestor of  $u$  in the tree. (p128)**

$(u, v)$  where  $u$  is an ancestor of  $v$  in the tree.

$(u, v)$  where  $v$  is an predecessor of  $u$  in the tree.

None of above

### Question # 21

**Cross edge is?**

$(u, v)$  where  $u$  and  $v$  are not ancestor of one another

$(u, v)$  where  $u$  is ancestor of  $v$  and  $v$  is not descendent of  $u$ .

**$(u, v)$  where  $u$  and  $v$  are not ancestor or descendent of one another (p129)**

$(u, v)$  where  $u$  and  $v$  are either ancestor or descendent of one another.

### Question # 22

If you find yourself in maze the better traversal approach will be?

Select correct option:

BFS

**BFS and DFS both are valid (p119)**

Level order

DFS

**Question # 23**

In digraph  $G=(V,E)$  ;G has cycle if and only if

Select correct option:

The DFS forest has forward edge.

**The DFS forest has back edge (p131)**

The DFS forest has both back and forward edge

BFS forest has forward edge

**Question # 24**

What is generally true of Adjacency List and Adjacency Matrix representations of graphs?

Select correct option:

Lists require less space than matrices but take longer to find the weight of an edge  $(v1,v2)$

**Lists require less space than matrices and they are faster to find the weight of an edge  $(v1, v2)$  (p116)**

Lists require more space than matrices and they take longer to find the weight of an edge  $(v1, v2)$

Lists require more space than matrices but are faster to find the weight of an edge  $(v1, v2)$

<http://cs-mcqs.blogspot.com/2012/06/data-structures-algorithms-multiple.html>

**Question No: 25**

Although it requires more complicated data structures, **Prim's algorithm** for a minimum spanning tree is **better** than **Kruskal's** when the graph has a **large number** of vertices.

**True**

False

**Question No: 26**

If a problem is in NP, it must also be in **P**.

True

**False (p178)**

unknown

**Question No: 27**

If a problem is in NP-complete, it must also be in **NP**.

**True**

False

**Question No: 28**

Maximum number of vertices in a Directed Graph may be  $|V^2|$

**True**

False

**Question No: 29**

The Huffman algorithm finds a (n) \_\_\_\_\_ solution.

**Optimal (Reference)**

Non-optimal

Exponential

Polynomial

**Question No: 30**

The Huffman algorithm finds an **exponential** solution

True

**False (Reference)**

**Question No: 31**

The Huffman algorithm finds a **polynomial** solution

True

**False (Reference)**

**Question No: 32**

The codeword assigned to characters by the Huffman algorithm have the property that no codeword is the **postfix** of any other. True **False**

**Question No: 33**

The codeword assigned to characters by the Huffman algorithm have the property that no codeword is the **prefix** of any other. **True (p101)** False

**Prefix Property:**

The codewords assigned to characters by the Huffman algorithm have the property that no codeword is a prefix of any other:

**Question No: 34**

Shortest path problems can be solved efficiently by modeling the road map as a graph. **True** False

**Question No: 35**

Dijkstra's algorithm is operates by maintaining a subset of vertices. **True** False

**Question No: 36**

Merge sort is stable sort, but not an in-place algorithm **True (p54)** False

**Question No: 37**

In counting sort, once we know the ranks, we simply \_\_\_\_\_ numbers to their final positions in an output array.  
Delete **copy (p57)** Mark arrange

**Question No: 38**

Dynamic programming algorithms need to store the results of intermediate sub-problems. **True (p75)** False

**Question No: 39**

A  $p \times q$  matrix A can be multiplied with a  $q \times r$  matrix B. The result will be a  $p \times r$  matrix C. There are  $(p \cdot r)$  total entries in C and each takes \_\_\_\_\_ to compute.

$O(q)$   **$O(1)$  (p84)**  $O(n^2)$   $O(n^3)$

**Question No: 40**

**6. Due to left-complete nature of binary tree, heaps can be stored in**

Link list

Structure

**Array (p40)**

None of above

**Question No: 41**

Which of the following is calculated with **big O notation**?

Lower bounds

**Upper bounds**

Both upper and lower bound

Medium bounds

- The definition of  $\Theta$ -notation relies on proving both a lower and upper asymptotic bound.
- The O-notation is used to state only the asymptotic upper bounds.

**Question No: 42**

Merge sort makes two recursive calls. Which statement is true after these recursive calls finish, but before the merge step?

The array elements form a heap

**Elements in each half of the array are sorted amongst themselves**

Elements in the first half of the array are less than or equal to elements in the second half of the array

None of the above

**Question No: 43**

Who invented Quick sort procedure?

**Hoare** Sedgewick Mellroy Coreman

**Question No: 44**

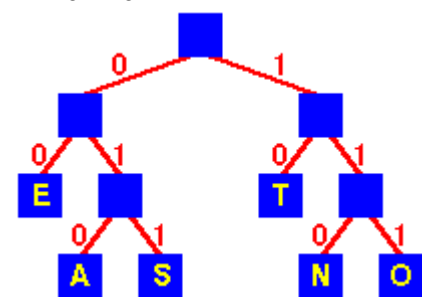
Consider the following Huffman Tree. The binary code for the string **TEA** is:

**10 00 010**

011 00 010

10 00 110

11 10 110



**String Encoding**

TEA 10 00 010

SEA 011 00 010

TEN 10 00 110

**Question No: 45**

Can an adjacency matrix for a directed graph ever not be square in shape?

Yes **No**

- No. since we want to describe the relationship between each node and each other node, we need precisely  $n^2$  matrix entries.

**Question No: 46**

One of the clever aspects of heaps is that they can be stored in arrays without using any \_\_\_\_\_

**Pointers (p40)** constants variables functions

**Question No: 47**

Merge sort requires extra array storage. **True (p54)** False

- Mergesort is a stable algorithm but **not** an in-place algorithm. It requires extra array storage.

**Question No: 48**

Non-optimal or greedy algorithm for money change takes \_\_\_\_\_

**O(k) (p99)** O(kN) O(2k) O(N)

**Question No: 49**

The Huffman codes provide a method of encoding data **inefficiently** when coded using ASCII standard.

True **False (p99)**

- The Huffman codes provide a method of encoding data **efficiently**.

**Question No: 50**

Using ASCII standard the string "abacdaacacwe" will be encoded with \_\_\_\_\_ bits

Select correct option:

64  
128  
**96** (p101 12x8=96)  
120

**Question No: 51**

Using ASCII standard the string abacdaacac will be encoded with \_\_\_\_\_ bits.

**80** (p99) 160 320 100

- Consider the string “ abacdaacac”. if the string is coded with ASCII codes, the message length would be  $10 \times 8 = 80$  bits.

**Question No: 52**

Using ASCII standard the string abacdaacac will be encoded with 160 bits.

True **False** (p99)

**Question No: 53**

Using ASCII standard the string abacdaacac will be encoded with 320 bits.

True **False** (p99)

**Question No: 54**

Using ASCII standard the string abacdaacac will be encoded with 100 bits.

True **False** (p99)

**Question No: 55**

Using ASCII standard the string abacdaacac will be encoded with 32 bytes.

True **False** (p99)

**Question No: 56**

The greedy part of the Huffman encoding algorithm is to first find two nodes with **smallest** frequency.

**True** (p100) False

**Question No: 57**

The greedy part of the Huffman encoding algorithm is to first find two nodes with **character** frequency.

True **False** (p100)

**Question No: 58**

The greedy part of the Huffman encoding algorithm is to first find two nodes with **larger** frequency.

True **False**

**Question No: 59**

Dijkstra’s single source shortest path algorithm works if all edges weights are **non-negative** and **there are no negative** cost cycles. True **False**

**Question No: 60**

Dijkstra s single source shortest path algorithm works if all edges weights are **non-negative** and **there are no negative** cost cycles. **True** (p159) False

**Question No: 61**

Dijkstra s single source shortest path algorithm works if all edges weights are **negative** and **there are no negative** cost cycles. True **False**

**Question No: 62**

Floyd-Warshall algorithm is a dynamic programming algorithm; the genius of the algorithm is in the clever recursive formulation of the shortest path problem. **True** (p162) False

**Question No: 63**

Floyd-Warshall algorithm, as in the case with DP algorithms, we avoid recursive evaluation by generating a table for  $d_{ij}^{(k)}$

**True (p164)**

False

**Question No: 64**

The term coloring came from the original application which was in **map drawing**. **True (p173)** False

The term “coloring” came from the original application which was in **architectural design**. True **False**

**Question No: 65**

In the **clique cover** problem, for two vertices to be in the same group, they must be \_\_\_\_\_ each other.

Apart from Far from Near to **Adjacent to (p176)**

**Question No: 66**

In the clique cover problem, for two vertices to be in the same group, they **must be adjacent** to each other.

**True** False

**Question No: 67**

In the **clique cover** problem, for two vertices to be in the same group, they **must be apart** from each other.

True **False (p176)**

**Question No: 68**

The difference between Prim's algorithm and Dijkstra's algorithm is that Dijkstra's algorithm **uses a different** key.

**True (p156)** False

**Question No: 69**

The difference between Prim's algorithm and Dijkstra's algorithm is that Dijkstra's algorithm **uses a same** key.

True **False (p156)**

**Question No: 70**

You have an adjacency list for  $G$ , what is the time complexity to compute graph transpose  $G^T$ ?

**$(V + E)$  (p138)**

**Question No: 71**

Given an adjacency list for  $G$ , it is possible to compute  $G^T$  in  $\Theta(V + E)$  time.

**It takes  $O(\log V)$  to extract a vertex from the priority queue.**

**Question No: 72**

Overall time for Kruskal is  $\Theta(E \log E) = \Theta(E \log V)$  if the graph is sparse. **(p149) True**

**Question No: 73**

An optimization problem is one in which you want to find,

Not a solution

An algorithm

Good solution

**The best solution**



**Question No: 74**

Although it requires more complicated data structures, Prim's algorithm for a minimum spanning tree is better than Kruskal's when the graph has a large number of vertices.

**True**

False

**Question No: 75**

If a graph has  $v$  vertices and  $e$  edges then to obtain a spanning tree we have to delete

$v$  edges.

$v - e + 5$  edges

$v + e$  edges.

**None of these**

**Question No: 76**

Huffman algorithm uses a greedy approach to generate an **antefix code** T that minimizes the expected length  $B(T)$  of the encoded string. True **False (p102)**

**Question No: 77**

Huffman algorithm uses a greedy approach to generate a **postfix code** T that minimizes the expected length  $B(T)$  of the encoded string. True **False (p102)**

**Question No: 78**

Huffman algorithm uses a greedy approach to generate a **prefix code** T that minimizes the expected length  $B(T)$  of the encoded string. **True (p102)** False

**Question No: 79**

Bellman-Ford allows negative weights edges and negative cost cycles. True **False (p159)**

- Bellman-Ford allows negative weights edges and no negative cost cycles.

**Question No: 80**

We do sorting to,

keep elements in random positions

keep the algorithm run in linear order

keep the algorithm run in  $(\log n)$  order

**keep elements in increasing or decreasing order**

**Question No: 81**

After partitioning array in Quick sort, pivot is placed in a position such that

**Values smaller than pivot are on left and larger than pivot are on right (Ref)**

Values larger than pivot are on left and smaller than pivot are on right

Pivot is the first element of array

Pivot is the last element of array

**Question No: 82**

Dynamic programming algorithms need to store the results of intermediate sub-problems. **True** False

**Question No: 83**

Which statement is true?

If a dynamic-programming problem satisfies the optimal-substructure property, then a locally optimal solution is globally optimal.

**If a greedy choice property satisfies the optimal-substructure property, then a locally optimal solution is globally optimal.**

Both of above

None of above

**Question No: 84**

What **general property** of the list indicates that the graph has an **isolated vertex**?

There is Null pointer at the end of list.

**The Isolated vertex is not handled in list.**

Only one value is entered in the list.

There is at least one null list.

**Question No: 85**

**Depth first search** is **shortest path** algorithm that works on **un-weighted** graphs. True

**False (p153)**

- The **breadth-first-search** algorithm is a shortest-path algorithm that works on **un-weighted** graphs.

**Question No: 86**

Which is true statement?

Select correct option:

**Breadth first search is shortest path algorithm that works on un-weighted graphs (p153)**

Depth first search is shortest path algorithm that works on un-weighted graphs.

Both of above are true.

None of above are true.

(1) In Prim's algorithm, the additional information maintained by the algorithm is the **length of the shortest edge** from vertex  $v$  to points already in the tree.

a) True

**b) False**

c) unknown

(2) Although it requires more complicated data structures, Prim's algorithm for a minimum spanning tree is better than Kruskal's when the graph has a **large number of vertices**.

**a) True**

b) False

c) unknown

(3) If a problem is NP-complete, it must also be in NP.

**a) True**

b) False

c) unknown

(4) Which statement is true?

(i) The running time of Bellman-Ford algorithm is  $T(V^2)$

(ii) Both Dijkstra's algorithm and Bellman-Ford are based on performing **repeated relaxations**

(iii) The 0-1 knapsack problem is hard to solve

Only i

Only iii

Both i and iii

**All of these**

5) Which of the following arrays represent **descending (max) heaps**?

i. [10,7,7,2,4,6]

ii. [10,7,6,2,4,7]

iii. [10,6,7,2,4,6]

iv. [6,6,7,2,4,10]

**Only ii**

Only iv

Both ii and iv

Both i and iii

6. Which of the following statement(s) is/are correct?

(a)  $O(n \log n + n^2) = O(n^2)$ .

(b)  $O(n \log n + n^2) = O(n^2 \log 2n)$

(c)  $O(c n^2) = O(n^2)$  where  $c$  is a constant.

(d)  $O(c n^2) = O(c)$  where  $c$  is a constant.

(e)  $O(c) = O(1)$  where  $c$  is a constant.

**Only (a) & (e)**

Both (c) and (e)

7. Which of the shortest path algorithms would be most appropriate for finding paths in the graph with **negative edge weights and cycles**?

i. Dijkstra's Algorithm

ii. Bellman-Ford Algorithm

iii. Floyd Warshall Algorithm

Only ii

Only iii

**Both ii & iii**

9. Suppose we have two problems A and B. Problem A is polynomial-time reducible and problem B is NP-complete. If we reduce problem A into B then problem A becomes NP-complete **Yes** No

12. Edge (u, v) is a forward edge if u is a proper descendant of v in the tree

**v is a proper descendant of u in the tree**

None of these

14. If, in a DFS forest of digraph  $G = (V, E)$ ,  $f[u] = f[v]$  for an edge  $(u, v) \in E$  then the edge is called

**Back edge**

Forward edge

Cross Edge

Tree Edge

None of these

16. Best and worst case times of an algorithm may be same. **True** False

17. Can an adjacency matrix for a directed graph ever not be square in shape? **Yes** No

1. In which order we can sort?

Increasing order only      decreasing order only

**Increasing order or decreasing order**

both at the same time

3. In the analysis of **Selection algorithm**, we make a number of passes, in fact it could be as many as,

$T(n)$

$T(n/2)$

**$\log n$  (p37)**

$n/2 + n/4$

4. How much time **merge sort** takes for an array of numbers?

$T(n^2)$

$T(n)$

$T(\log n)$

**$T(n \log n)$  (p40)**

7. Sieve Technique applies to problems where we are interested in finding a single item from a larger set of \_\_\_\_

**n items (p34)**

phases

pointers

constant

8. The sieve technique works in \_\_\_\_\_ as follows

**Phases (p34)**

numbers

integers

routines

9. For the heap sort, access to nodes involves simple \_\_\_\_\_ operations.

**Arithmetic**

binary

algebraic

logarithmic

10. The analysis of Selection algorithm shows the total running time is indeed \_\_\_\_\_ in n,

Arithmetic

geometric

**linear (p39)**

orthogonal

12. Slow sorting algorithms run in,

**$T(n^2)$  (p39)**

$T(n)$

$T(\log n)$

$T(n \log n)$

13. A heap is a left-complete binary tree that conforms to the

Increasing order only

decreasing order only

**heap order**

$(\log n)$  order

14. For the heap sort we store the tree nodes in  
**Level-order traversal (p40)** in-order traversal pre-order traversal post-order traversal

20: In Sieve Technique we do not know which item is of interest **True (p34)** False

22: Divide-and-conquer as breaking the problem into a small number of  
Pivot Sieve **smaller sub problems (p34)** Selection

23: For the sieve technique we solve the problem,  
**Recursively (p34)** mathematically precisely accurately

25: The reason for introducing **Sieve Technique** algorithm is that it illustrates a very important special case of,  
**Divide-and-conquer (p34)** decrease and conquer greedy nature 2-dimension Maxima

32. Sorting is one of the few problems where provable \_\_\_\_\_ bounds exists on how fast we can sort,  
Upper **Lower (p39)** Average log n

34: Sieve Technique can be applied to selection problem? **True** False

Heaps can be stored in arrays without using any pointers; this is due to the \_\_\_ nature of the binary tree,  
**Left-complete** right-complete tree nodes tree leaves

38: How many elements do we eliminate in each time for the Analysis of Selection algorithm?  
**n / 2 elements (p36)**  $(n / 2) + n$  elements  $n / 4$  elements  $2n$  elements

42: The sieve technique is a special case, where the number of sub problems is just  
5 Many **1 (p34)** few

### Question # 1

For the Sieve Technique we take time  
**T(nk) (p34)**  $T(n / 3)$   $n^2$   $n/3$

### Question # 2

The number of nodes in a complete binary tree of height h is

Select correct option:

**$2^{(h+1)} - 1$**

$2 * (h+1) - 1$

$2 * (h+1)$

$((h+1) ^ 2) - 1$

### Question No: 1

Random access machine or RAM is a/an

Machine build by Al-Khwarizmi

Mechanical machine

Electronics machine

**Mathematical model (p10)**

### Question No: 2

Analysis of Selection algorithm ends up with,

**T(n)**

T(1 / 1 + n)

T(n / 2)

T((n / 2) + n)

**Question # 6**

Continuation sort is suitable to sort the elements in range 1 to k

1. K is Large    2. K is not known    3. K may be small or large    **4. K is small (p57)****Question # 5**

Counting sort is suitable to sort the elements in range 1 to k:

K is large    **K is small**    K may be large or small    None**Question # 10**

Continuing sort has time complexity of?

**1. O(n) (p58)**    2. O(n+k)    3. O(nlogn)**Question # 11**

Counting sort has time complexity:

**O(n) (p58)**    O(n+k)    O(k)    O(nlogn)**Question # 6**

Memoization is :

To store previous results for further use.

**To avoid unnecessary repetitions by writing down the results of recursive calls and looking them again if needed later. (p74)**

To make the process accurate

None of the above

**Question # 9**In Quick sort algorithm, constants hidden in  $T(n \lg n)$  are:Large    Medium    Not known    **small (Ref)****Question # 12**

Quick sort is based on divide and conquer paradigm; we divide the problem on base of pivot element and:

**There is explicit combine process as well to conquer the solution.**

No work is needed to combine the sub-arrays, the array is already sorted

Merging the subarrays

None of above.

**Question # 13**

In RAM model instructions are executed

**One after another (p10)**

Parallel

Concurrent

Random

**Question # 14**In the analysis of Selection algorithm, we eliminate a constant fraction of the array with each phase; we get the **convergent** \_\_\_\_\_ series in the analysis,

linear          arithmetic          **geometric (p37)**          exponent

**Question No: 2**

\_\_\_\_\_ is a graphical representation of an algorithm

Σ notation          Θnotation          **Flowchart (Ref)**          Asymptotic notation

**Question No: 3**

A RAM is an idealized machine with \_\_\_\_\_ random-access memory.

256MB          512MB          **An infinitely large (p10)**          100GB

**Question No: 4**

What type of instructions Random Access Machine (RAM) can execute? Choose best answer

Algebraic and logic

Geometric and arithmetic

**Arithmetic and logic (p10)**

Parallel and recursive

**Question No: 5**

What will be the total number of **max comparisons** if we run **brute-force maxima** algorithm with n elements?

**n<sup>2</sup> (p14)**          2n/n          n          8n

**Question No: 6**

What is the solution to the recurrence  $T(n) = T(n/2) + n$ .

O(logn)          **O(n)**          O(nlogn)          O(n<sup>2</sup>)

**Question No: 7**

Consider the following code:

```
For(j=1; j<n;j++)
  For(k=1; k<15;k++)
    For(l=5; l<n; l++)
    {
      Do_something_constant();
    }
```

What is the order of execution for this code.

**O(n)**

O(n<sup>3</sup>)

O(n<sup>2</sup> log n)

O(n<sup>2</sup>)

**Question No: 8**

Consider the following Algorithm:

```
Factorial (n){
  if (n=1)
    return 1
  else
    return (n * Factorial(n-1))
}
```

Recurrence for the following algorithm is:

$T(n) = T(n-1) + 1$

$T(n) = nT(n-1) + 1$

$$T(n) = T(n-1) + n$$

$$T(n) = T(n-1) + 1$$

**Question No: 9** -

What is the total time to heapify?

**$O(\log n)$  (p43)**

$O(n \log n)$

$O(n^2 \log n)$

$O(\log^2 n)$

**Question No: 10**

When we call heapify then at each level the comparison performed takes time

**It will take  $\Theta(1)$  (p43)**

Time will vary according to the nature of input data

It cannot be predicted

It will take  $\Theta(\log n)$

**Question No:**

In Quick sort, we don't have the control over the sizes of recursive calls

**-True (p49)**

-False

-Less information to decide

-Either true or false

**Question No: 12**

Is it possible to sort without making comparisons?

**Yes (p57)**

No

**Question No: 13**

If there are  $\Theta(n^2)$  entries in edit distance matrix then the total running time is

$\Theta(1)$

**$\Theta(n^2)$**

$\Theta(n)$

$\Theta(n \log n)$

**Question No: 14**

For Chain Matrix Multiplication we cannot use divide and conquer approach because,

**We do not know the optimum k (p86)**

We use divide and conquer for sorting only

We can easily perform it in linear time

Size of data is not given

**Question No: 15**

The Knapsack problem belongs to the domain of \_\_\_\_\_ problems.

**Optimization (p91)**

NP Complete

Linear Solution

Sorting

**Question No: 16**

Suppose we have three items as shown in the following table, and suppose the capacity of the knapsack is 50 i.e.  $W = 50$ .

Item	Value	Weight
1	60	10
2	100	20
3	120	30

The optimal solution is to pick

Items 1 and 2

Items 1 and 3

**Items 2 and 3**

None of these

## Quiz 5

### Question # 1

Theta asymptotic notation for  $T(n)$ :

Select correct option:

Set of functions described by:  $c_1g(n) \leq f(n)$  for  $c_1$  some constant and  $n \geq n_0$

Set of functions described by  $c_1g(n) \geq f(n)$  for  $c_1$  some constant and  $n \geq n_0$

Theta for  $T(n)$  is actually upper and worst case complexity of the code

**Set of functions described by:  $c_1g(n) \leq f(n) \leq c_2g(n)$  for  $c_1$  and  $c_2$  some constants and  $n \geq n_0$**

### Question # 2

A (an) \_\_\_\_\_ is a left-complete binary tree that conforms to the heap order

**Heap (page 40)**

Binary tree

Binary search tree

Array

### Question # 3

Consider the following Algorithm:  $Fun(n) \{ \text{if } (n=1) \text{ return } 1 \text{ else return } (n * Fun(n-1)) \}$  Recurrence for the above algorithm is: Select correct option:

$nT(n-1)+1$

**$2T(n-1)+1$**

$T(n-1)+cn$

$T(n-1)+1$

### Question # 4

The recurrence relation of Tower of Hanoi is given below  $T(n) = \{ 1 \text{ if } n=1 \text{ and } 2T(n-1) \text{ if } n > 1$  In order to move a tower of 5 rings from one peg to another, how many ring moves are required?

Select correct option: 16 10 **32** 31

### Question # 5

In Quick Sort Constants hidden in  $T(n \log n)$  are

1. Large

2. Medium

**3. Small (Reference)**

4. Not Known

### Question # 6

In stable sorting algorithm;

One array is used

In which duplicating elements are not handled.

More than one arrays are required.

**Duplicating elements remain in same relative position after sorting. (p54)**

### Question # 7

In in-place sorting algorithm is one that uses arrays for storage:

An additional array

**No additional array (p54)**

Both of above may be true according to algorithm

More than 3 arrays of one dimension



### Question # 8

Which may be a stable sort?

1. Merger
2. Insertion
3. Both above (p54)
4. None of the above

### Question # 9

An in place sorting algorithm is one that uses \_\_\_ arrays for storage

1. Two dimensional arrays
2. More than one array
3. No Additional Array (p54)
4. None of the above

### Question # 10

Quick sort is

Stable and In place

**Not stable but in place (p54)**

Stable and not in place

Sometime in place and sometime stable

### Question # 11

One Example of **in place** but **not stable** sort is

**Quick (p54)**      Heap      Merge      Bubble

### Question # 12

Which may be stable sort?

Bubble sort      Insertion sort      **both of above (p54)**

### Question # 13

Merge sort is stable sort, but not an in-place algorithm      **True (p54)**      False

An **in-place sorting** algorithm is one that uses **no additional array** for storage. A sorting algorithm is stable if duplicate elements remain in the same relative position after sorting.      **(p54)**

9   3   3'   5   6   5'   2   1   3''	unsorted
---------------------------------------	----------

1   2   3   3'   3''   5   5'   6   9	stable sort
---------------------------------------	-------------

1   2   3'   3   3''   5'   5   6   9	unstable
---------------------------------------	----------

**Bubble** sort, **insertion** sort and **selection** sort are **in-place** sorting algorithms.

**Bubble sort** and **insertion sort** can be implemented as **stable** algorithms but selection sort cannot (without significant modifications).

Mergesort is a **stable algorithm** but **not an in-place** algorithm. It requires **extra array** storage.

Quicksort is **not stable** but is an **in-place** algorithm.

Heapsort is an **in-place** algorithm but is **not stable**.